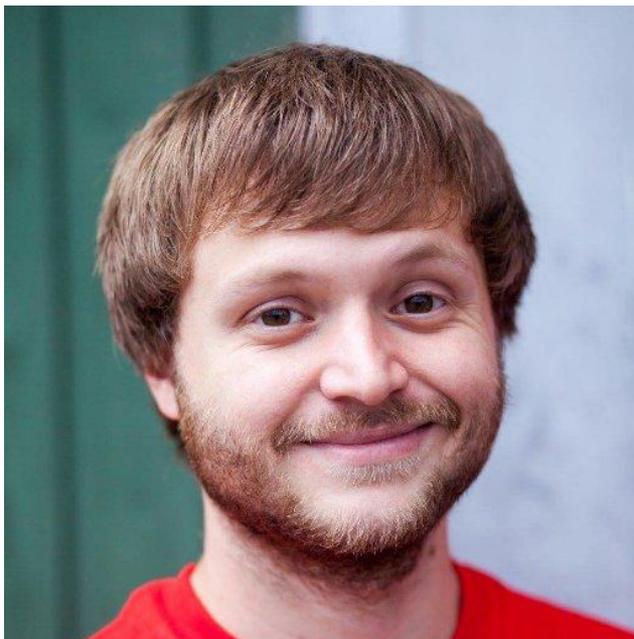


The Fundamentals Of Neural Networks



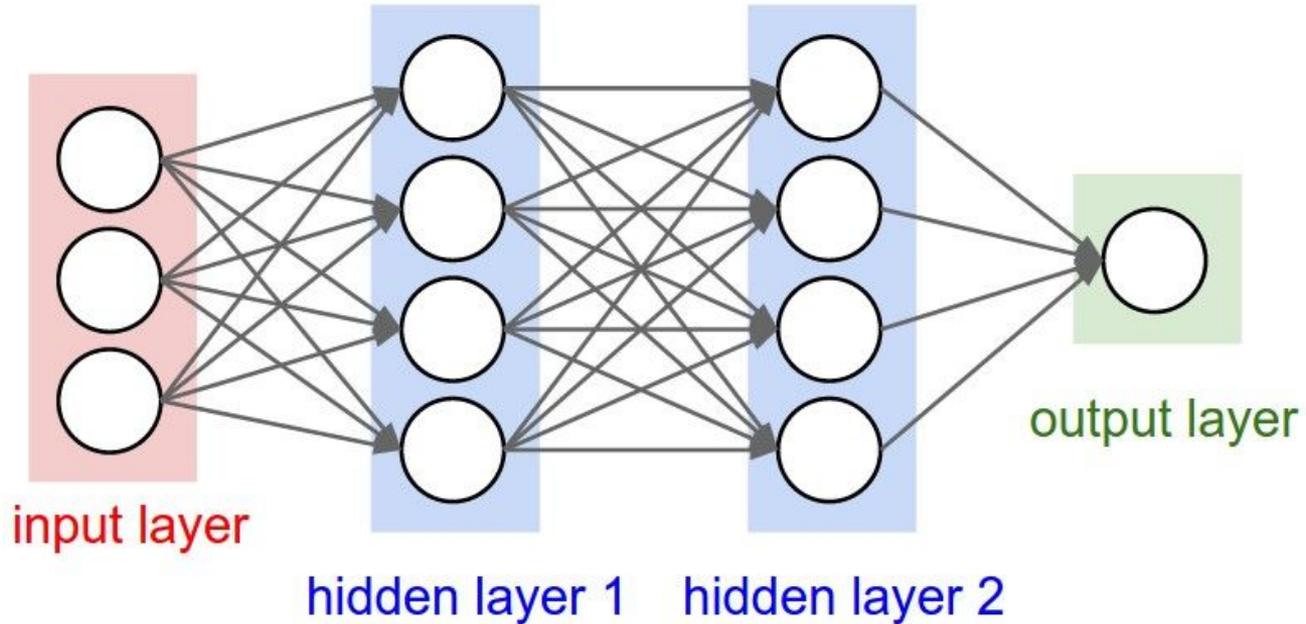
Chris Foster

Machine Learning

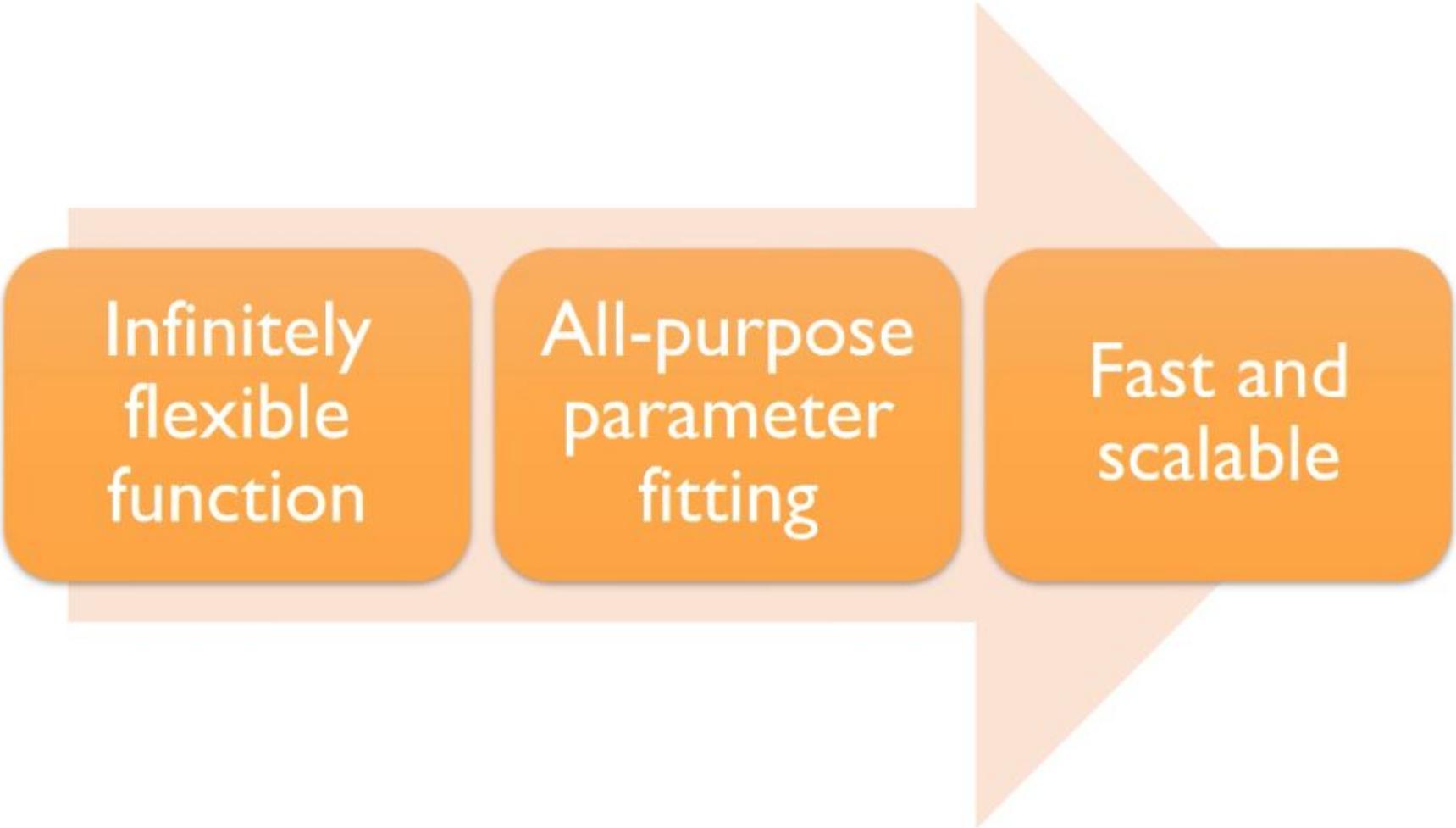
Web Development

Computer Security

Neural Network



“A computer system modeled on the human brain and nervous system”



Infinitely
flexible
function

All-purpose
parameter
fitting

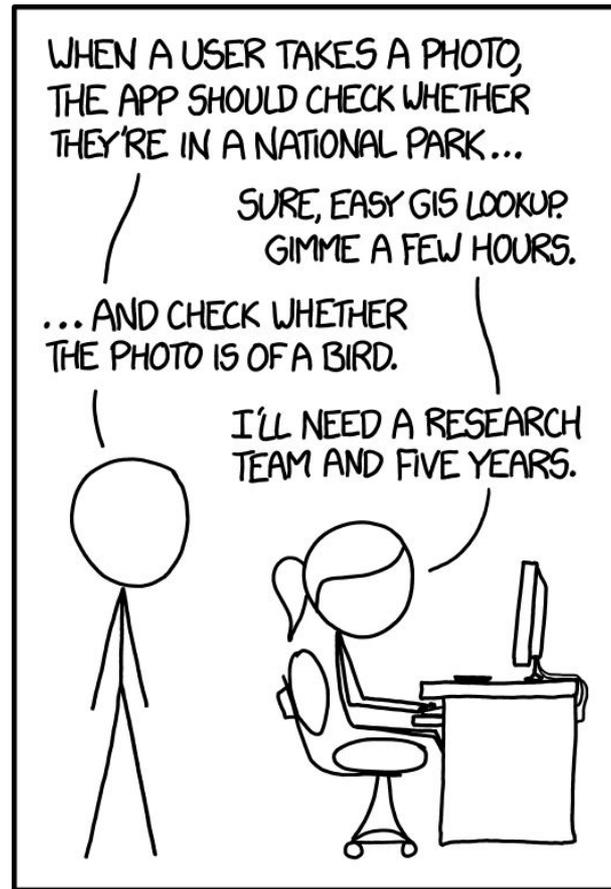
Fast and
scalable

How are Neural Networks different?

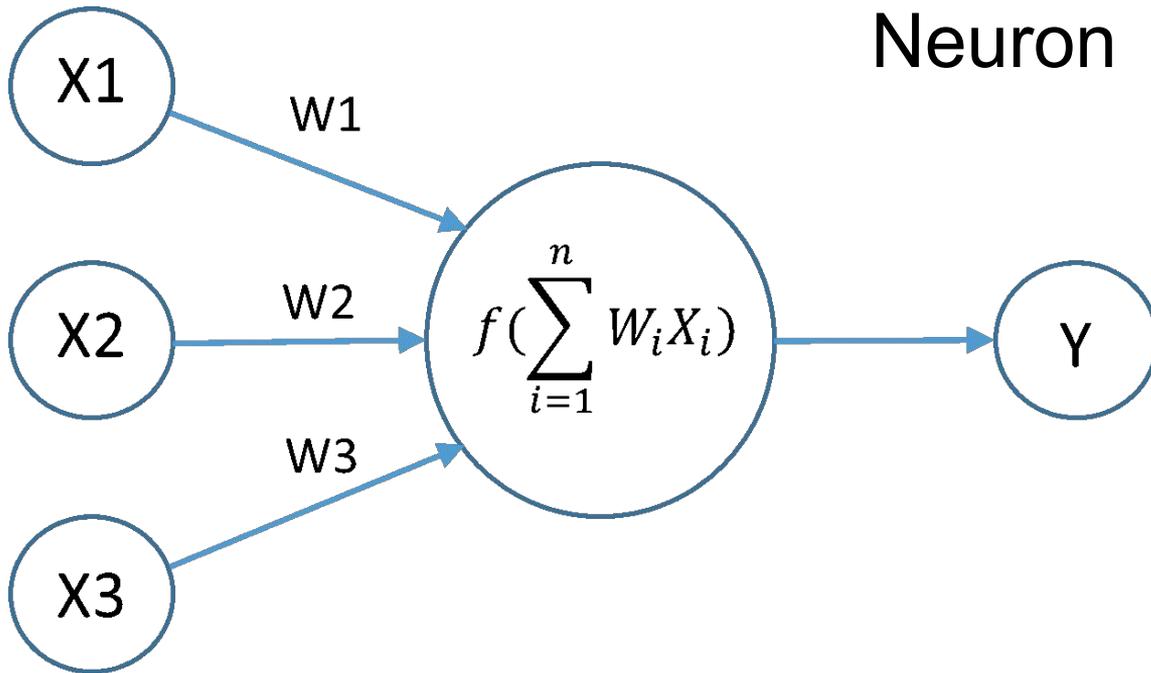
Applications

- Self Driving Cars
- Language Translation
- Sentiment Analysis
- Text Generation
- Image Generation
- Object Classification
- Neuroscience
- Image Enhancement
- Audio Transcription
- ...and much more!

Pattern Recognition Tasks



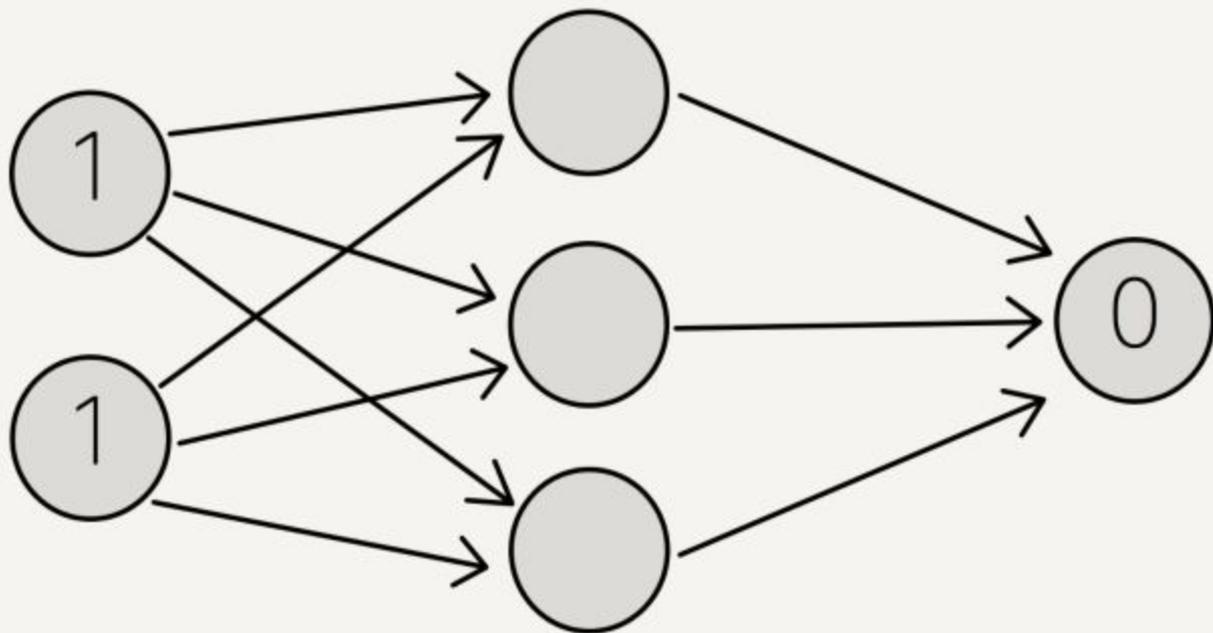
IN CS, IT CAN BE HARD TO EXPLAIN
THE DIFFERENCE BETWEEN THE EASY
AND THE VIRTUALLY IMPOSSIBLE.

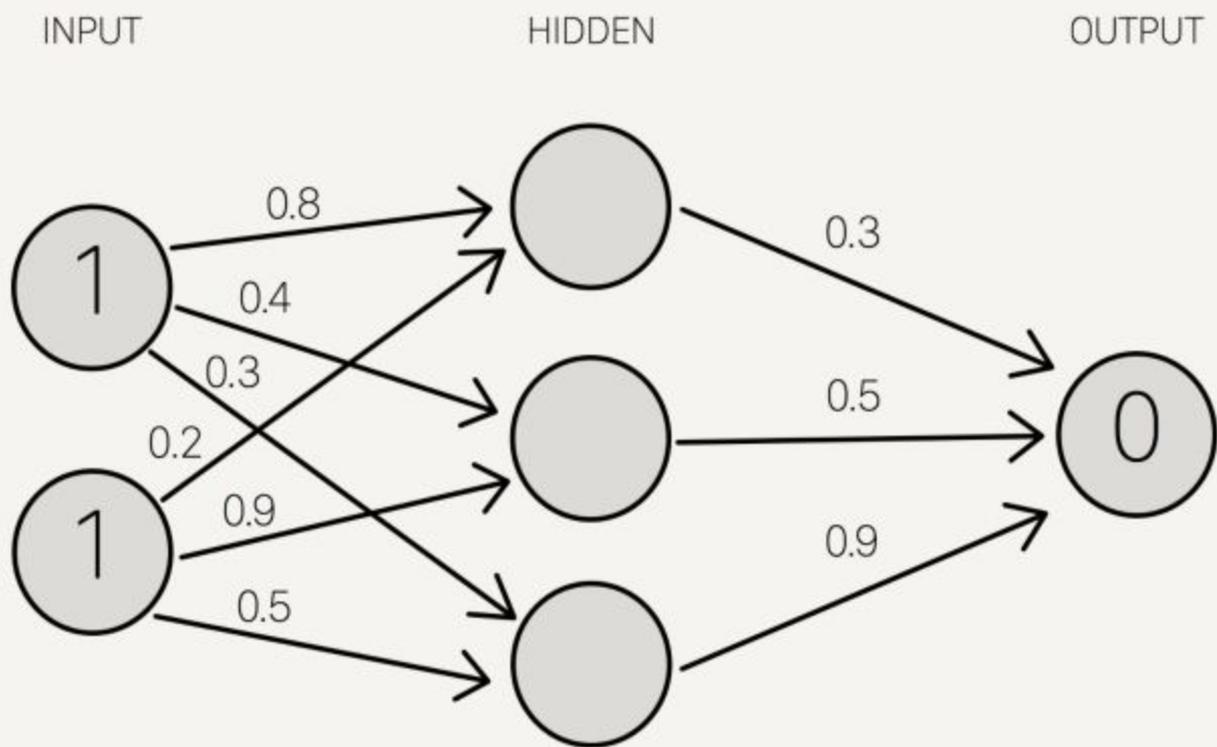


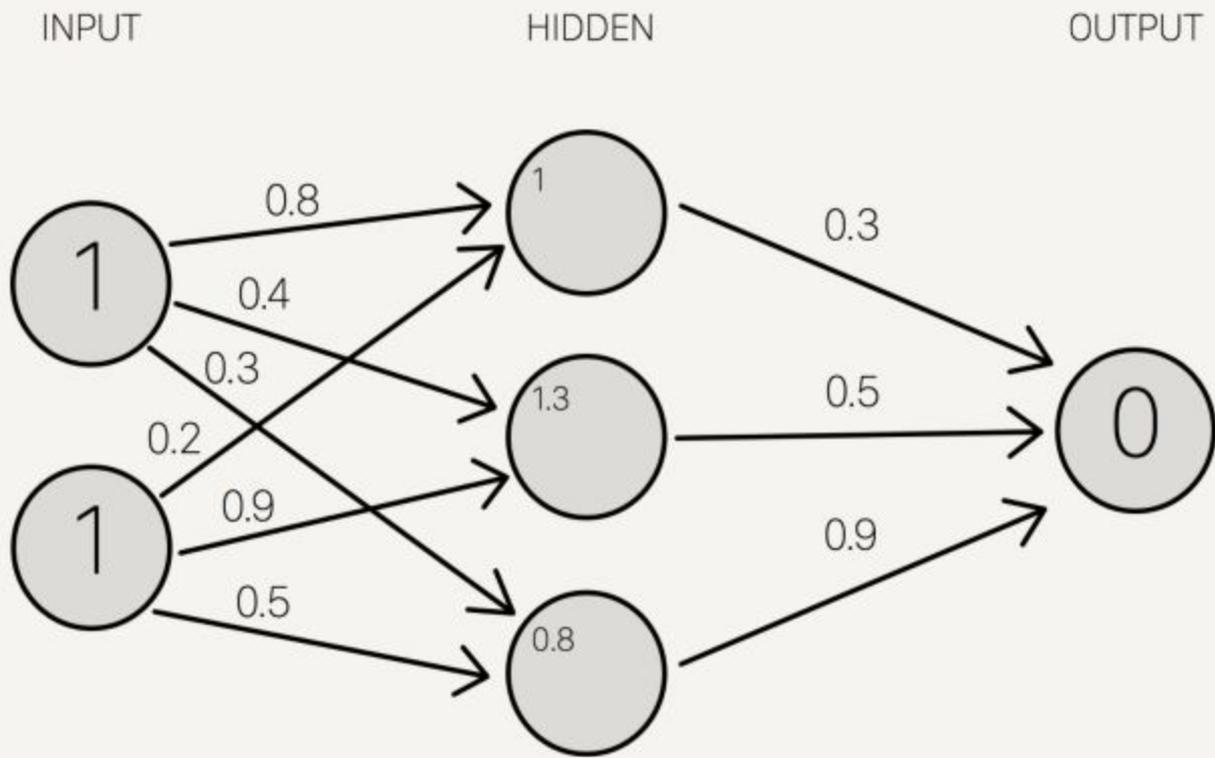
INPUT

HIDDEN

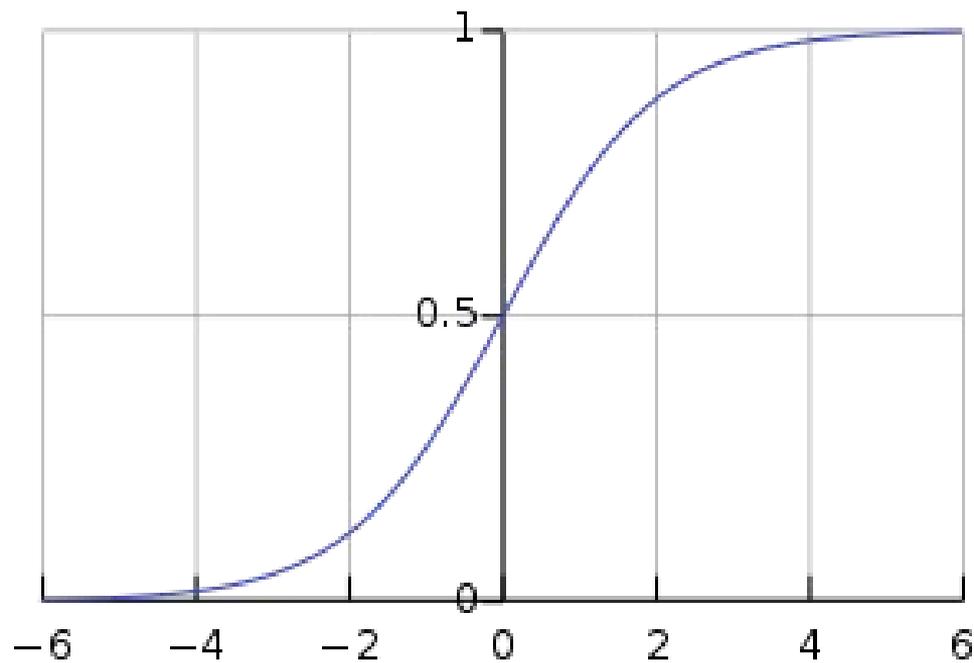
OUTPUT

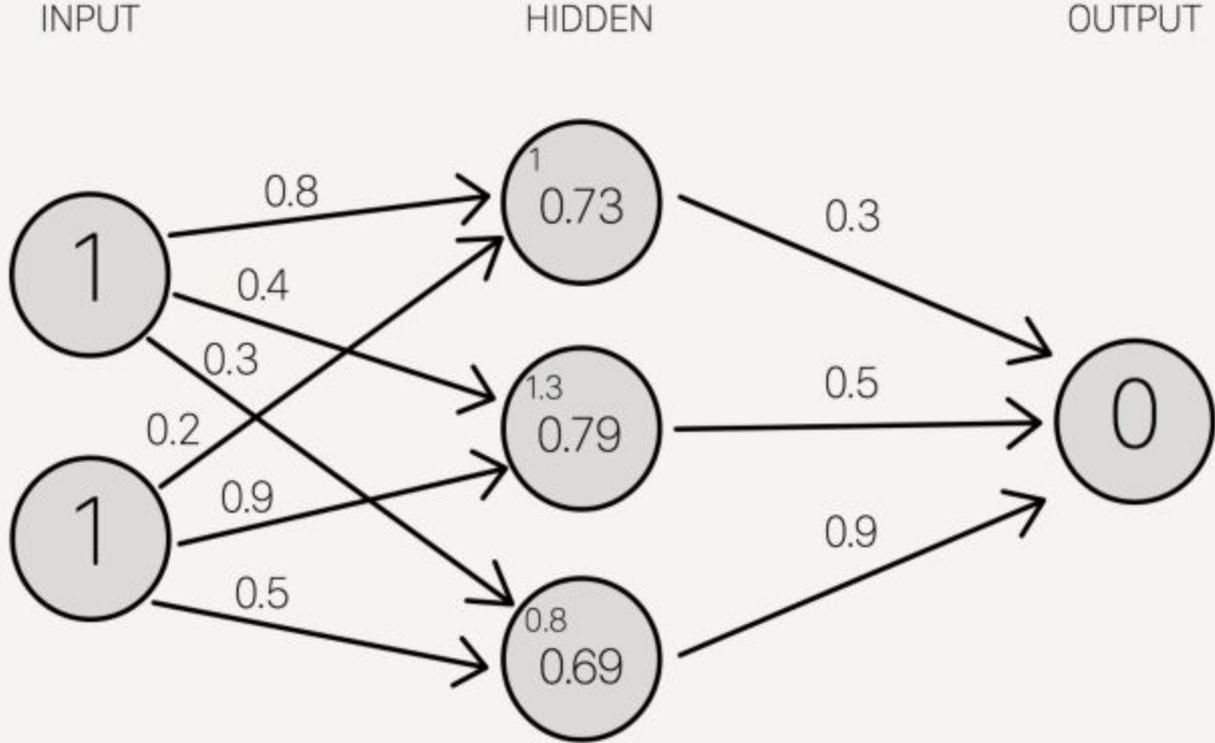


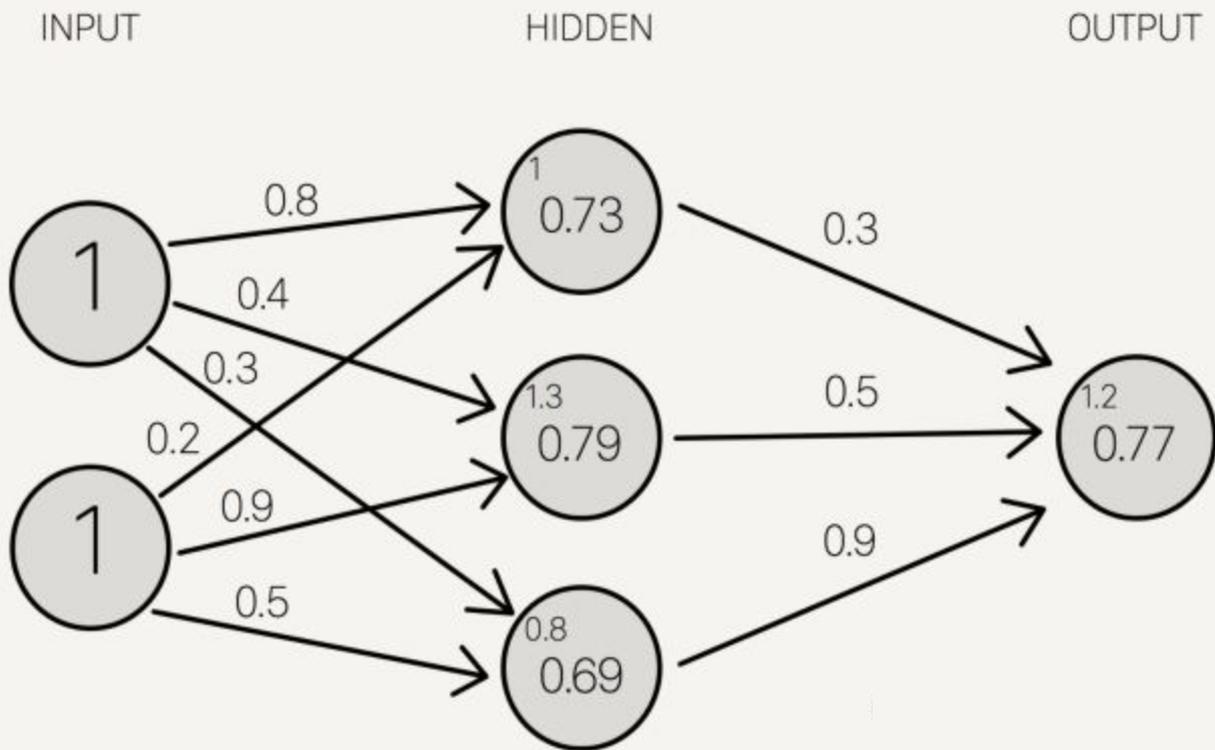




$$f(x) = \frac{1}{1 + e^{-x}}$$







$$net_{h1} = w_1 * i_1 + w_2 * i_2 + b_1 * 1$$

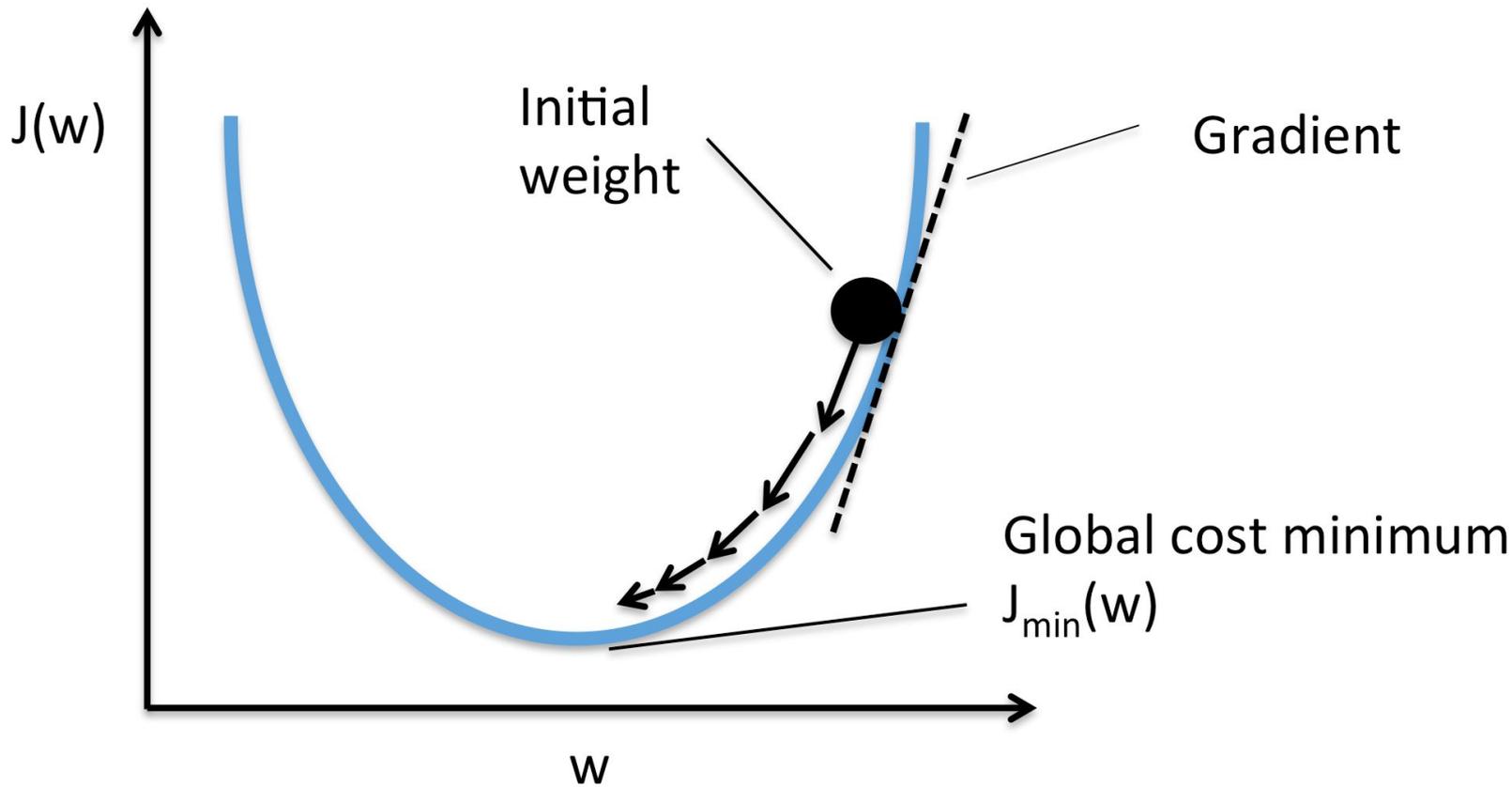
$$net_{h1} = 0.15 * 0.05 + 0.2 * 0.1 + 0.35 * 1 = 0.3775$$

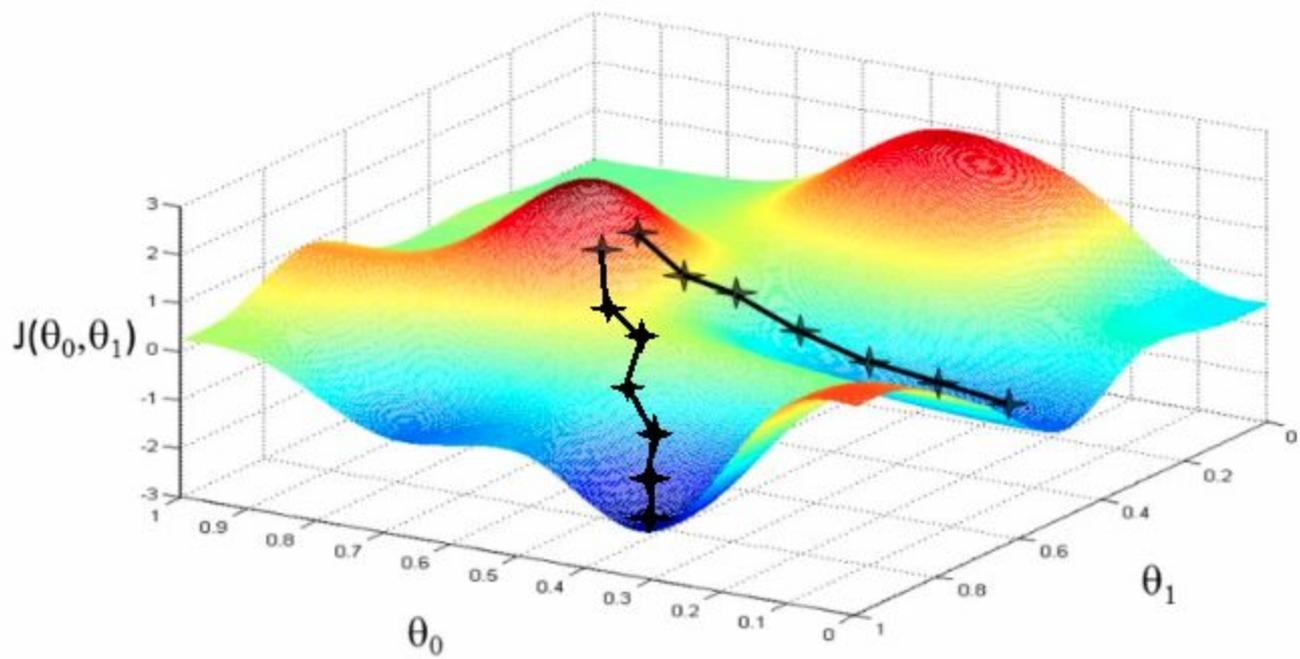
$$out_{h1} = \frac{1}{1+e^{-net_{h1}}} = \frac{1}{1+e^{-0.3775}} = 0.593269992$$

How do we get these weights?

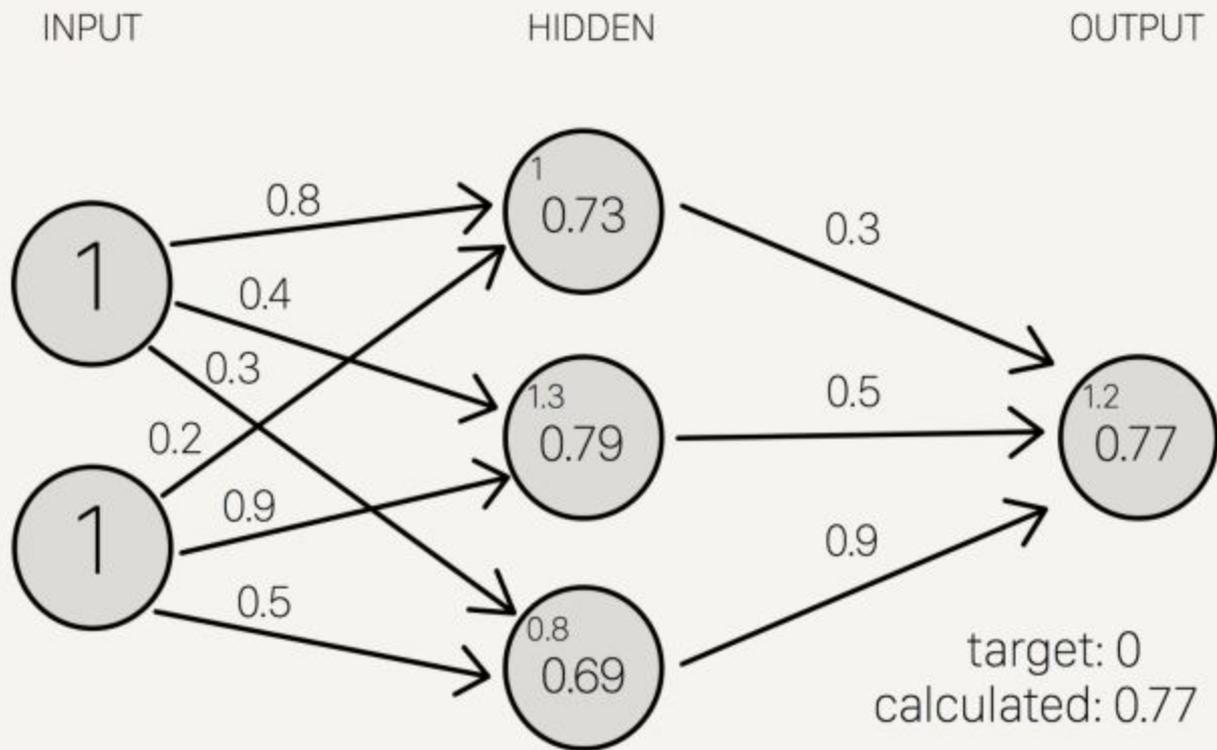
How do we get these weights?

Gradient Descent and Backpropagation





$$E_{total} = \sum \frac{1}{2} (target - output)^2$$



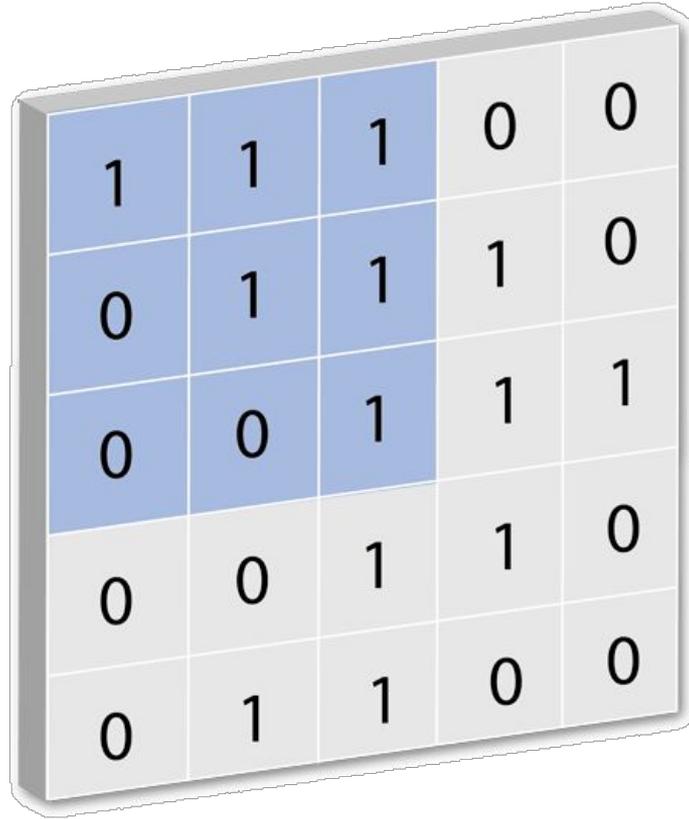
Workshop

Build your own network!

<http://tinyurl.com/mq7s7od>

Neural Networks can get a lot more complex

Convolutional Neural Networks

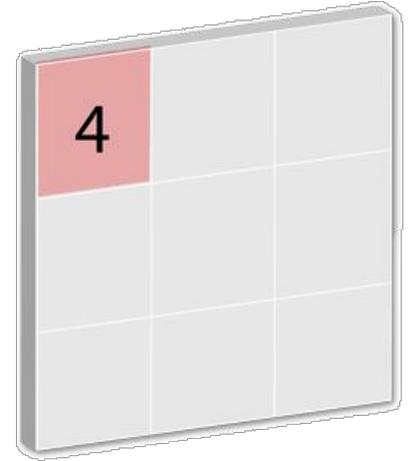


A 5x5 grid representing an input image. The grid contains the following values:

| | | | | |
|---|---|---|---|---|
| 1 | 1 | 1 | 0 | 0 |
| 0 | 1 | 1 | 1 | 0 |
| 0 | 0 | 1 | 1 | 1 |
| 0 | 0 | 1 | 1 | 0 |
| 0 | 1 | 1 | 0 | 0 |

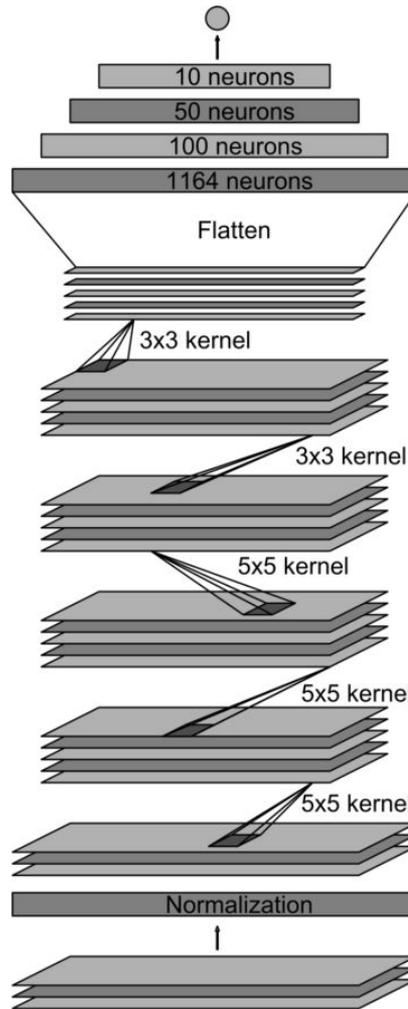
The 3x3 blue shaded region (kernel) covers the top-left portion of the grid, containing the values:

| | | |
|---|---|---|
| 1 | 1 | 1 |
| 0 | 1 | 1 |
| 0 | 0 | 1 |



A 3x3 grid representing the output feature map. The top-left cell is highlighted in red and contains the value 4.

| | | |
|---|--|--|
| 4 | | |
| | | |
| | | |



Output: vehicle control

Fully-connected layer
 Fully-connected layer
 Fully-connected layer

Convolutional
 feature map
 64@1x18

Convolutional
 feature map
 64@3x20

Convolutional
 feature map
 48@5x22

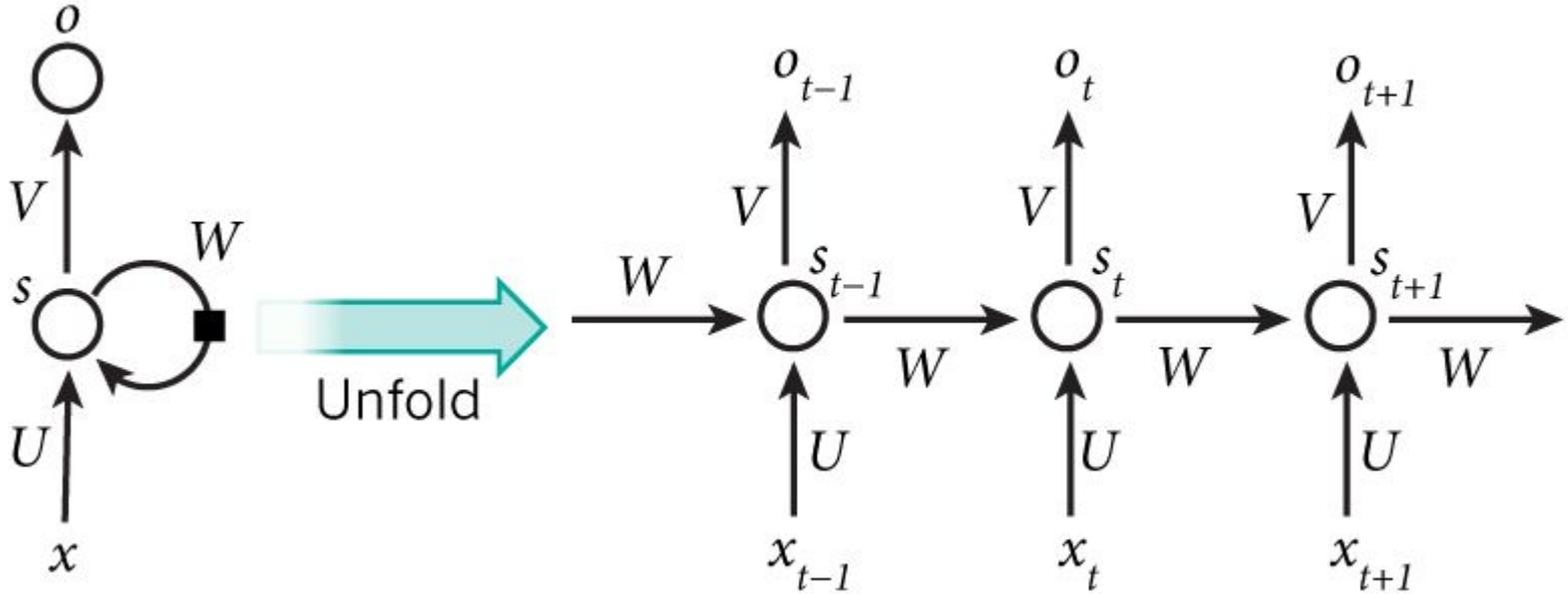
Convolutional
 feature map
 36@14x47

Convolutional
 feature map
 24@31x98

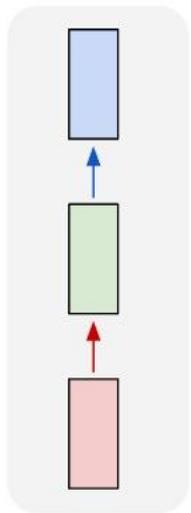
Normalized
 input planes
 3@66x200

Input planes
 3@66x200

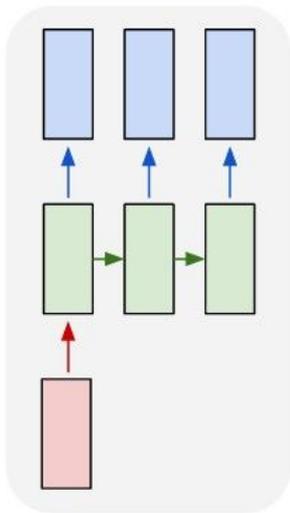
Recurrent Neural Networks



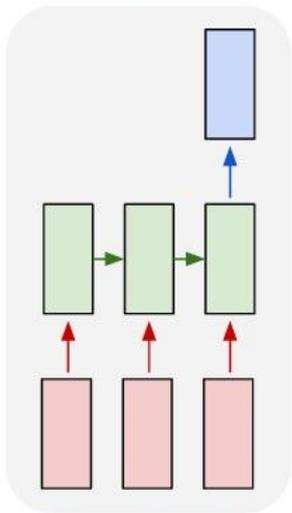
one to one



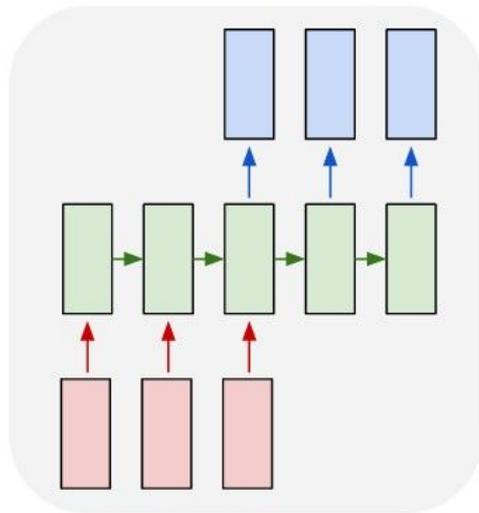
one to many



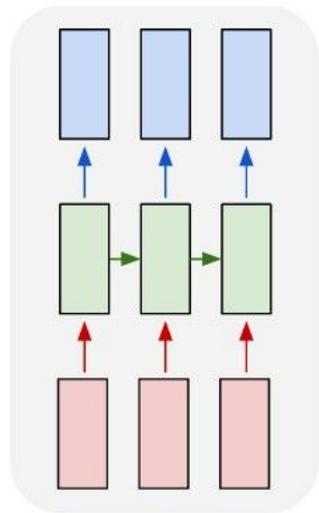
many to one

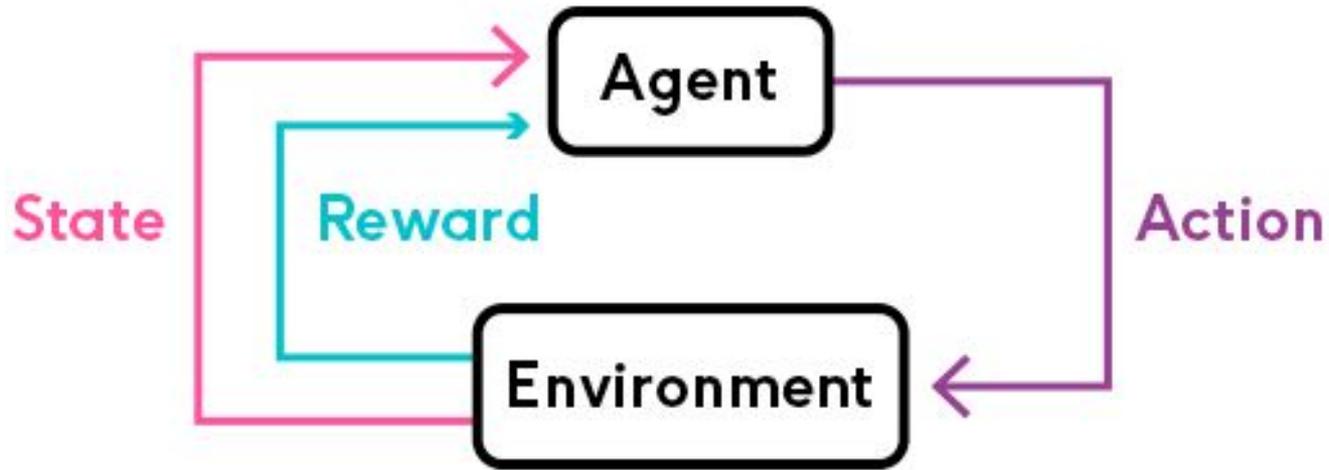


many to many



many to many





Reinforcement Learning

Workshop

Build an RNN!

<http://tinyurl.com/jvvm2d9>

Next Steps

- Keras - Neural Network LEGO coding
- Tensorflow - Efficient tensor computation library

- fast.ai - Developer focused Neural Network course
- Deep Learning Book - Rigorous Neural Networks

Thanks!

Sources

<http://cs231n.github.io>

<http://www.fast.ai>

<https://xkcd.com>

<https://stevenmiller888.github.io>

<https://commons.wikimedia.org>

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<https://sebastianraschka.com>

<https://medium.com/@eamonabraham>

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<http://machinelearningmastery.com>

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<https://devblogs.nvidia.com>

<http://karpathy.github.io>

<http://www.deeplearningbook.org>